XTRAPULP

Partitioning Irregular Graphs at the Trillion-Edge Scale

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Highlights

- We present XTRAPULP, a multi-constraint multi-objective distributed-memory partitioner based on PULP, a shared-memory label propagation-based graph partitioner
- Scales to 17 billion vertices and 1.1 trillion edges several orders-of-magnitude larger than any in-memory partitioner is able to process; partitions these graphs on 131,072 cores of *Blue Waters* in minutes
- Cut quality within small factor of state-of-the-art
- Code available:

https://github.com/HPCGraphAnalysis/PuLP interface also exists in Zoltan2 Trilinos package

Paper to appear in IPDPS 2017

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- Algorithm completes when no new updates possible; in large graphs, fixed iteration count



Label Propagation Partitioning Prior Work

Multilevel methods:

- [Wang et al., 2014] label prop to coarsen, METIS to partition
- [Meyerhenke et al., 2015] label prop to coarsen, KaFFPaE to partition
- Benefits: High relative quality
- Drawbacks: Overheads of multilevel framework

Single level methods:

- [Ugander and Backstrom, 2013] direct partition via constrained label prop
- [Vaquero et al.] dynamic partitioning via constrained label prop
- Benefits: Low overhead, high scalability
- Drawbacks: Low relative quality

Our original PULP implementation [Slota et al., 2014] showed quality near the former and scalability higher than the latter. How do we further scale for processing current and forthcoming massive-scale datasets (e.g. brain graphs, web crawls, social networks)?

$\underset{\text{Algorithm overview}}{\text{PuLP}}$

- XTRAPULP algorithm follows outline of original PULP
- Constrain: vertices and edges per part
- Minimize: global cut and cuts per part
- Iterate between satisfying various balance constraints and objectives

Initialize p partitions for Some number of iterations do Label propagation constraining vertices per part Refine partitions to minimize edge cut

for Some number of iterations **do** Label propagation constraining edges and cut edges per part Refine partitions to minimize edge cut

XtraPuLP

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Challenges Partitioning at the Trillion Edge Scale

- No longer can assume graph or part assignments fit in shared-memory; graph structure and part assignments need to be fully distributed
- MPI communication methods need to be as efficient as possible; up to O(m) data exchanged all-to-all among O(nprocs) tasks during each of O(100) iterations
- Parallelization methodology should account for degree skew and imbalance of large irregular graphs
- Real-time tracking of updates infeasible. At no point does any processing task have accurate global part information. Therefore, need to carefully control part assignment updates as tasks independently relabel their owned vertices

Implementation Methodology

- Storage and communication: we use the HPCGRAPH Framework [Slota et al., 2016] as a baseline; supplies efficient and scalable 1D graph representation
- Modify and optimize code for PageRank-like processing pattern; information is pulled in - i.e. vertex v updates its part assignment P(v) to reflect some optimal given known neighborhood information combined with assumed global information
- MPI+OpenMP parallelization; everything is done thread-parallel except for MPI calls
- But still need to address: How to control label propagation updates to balance communication requirements/accuracy/quality/etc?

Controlling Part Assignment

Our weighted label propagation algorithms update part assignments P(v) using a weighting function W(p), where v is more likely to join part p if p is underweight

$$P(v) = \max_{p}(W(p) \times |u \in N(v)| \text{ where } P(u) = p)$$
$$W(p) \propto \max(S_{max} - S(p), 0)$$

Algorithms require knowledge of global part sizes S(p) for balance/refinement - real-time global updates not feasible
 Instead, we approximate current sizes as A(p) using known global sizes, and per-task changes observed C(p) scaled by dynamic multiplier mult

$$A(p) = S(p) + mult \times C(p) \quad \text{are solved} \quad \text{in } (p) = S(p) + mult \times C(p) \quad \text{are solved} \quad \text{in } (p) = S(p) + mult \times C(p) \quad \text{are solved} \quad \text{in } (p) = S(p) + mult \times C(p) \quad \text{are solved} \quad \text{in } (p) = S(p) + mult \times C(p) \quad \text{are solved} \quad \text{in } (p) = S(p) + mult \times C(p) \quad \text{are solved} \quad \text{in } (p) = S(p) + mult \times C(p) \quad \text{are solved} \quad \text{in } (p) = S(p) + mult \times C(p) \quad \text{are solved} \quad \text{in } (p) = S(p) + mult \times C(p) \quad \text{are solved} \quad$$

Controlling Part Assignment - mult

- Consider *mult* to be the inverse of each task's *share* of allowed updates before part p becomes imbalanced
- A larger *mult* means each task will compute *A*(*p*) to be relatively larger, less likely to assign new vertices to *p*
- **E.g.** if mult = numTasks, each task can add $\frac{S_{max}-S(p)_{cur}}{numTasks}$ new vertices/edges/cut edge to part p
- We use two parameters X and Y to dynamically adjust mult as iterations progress; Y controls initial size of mult and X controls final size of mult

$$mult \leftarrow nprocs \times ((X - Y)(\frac{Iter_{\mathsf{cur}}}{Iter_{\mathsf{tot}}}) + Y)$$

We use Y = 0.25 and X = 1.0; each task can alter a part by $4 \times$ its share of updates initially but only by $1 \times$ its share finally , as a set of the state of the state

$\mathbf{X} \mathbf{T} \mathbf{R} \mathbf{A} \mathbf{P} \mathbf{U} \mathbf{L} \mathbf{P}$ using PageRank-like Algo Pattern

```
1: procedure PULPALG(Graph G(V, E), Parts P)
                                                                          ▷ Task Parallel
 2:
          S, C, A, mult \leftarrow init(P) \triangleright Initialize per-task part size data
 3:
          \langle S \rangle \leftarrow \mathsf{AllToAllExchange}(S)
                                                               \triangleright Initial global part sizes
 4:
        Q \leftarrow V
 5:
          while Q \neq \emptyset or Iter_{cur} < Iter_{tot} do
 6:
               for all v \in Q do
                                                                        ▷ Thread Parallel
 7:
                   for all \langle v, u \rangle \in E do
 8:
                        if P(v) = p \leftarrow update() then
 9:
                            C(p) \leftarrow update()
                                                                         ▷ Atomic update
10:
                             A(p) \leftarrow update()
11:
                            Q_{next} \leftarrow \langle v, P(v) \rangle
               \langle P \rangle \leftarrow \mathsf{AllToAllExchange}(Q_{next})
12:
                                                                   ▷ Update ghost parts
               \langle S \rangle \leftarrow \mathsf{AllToAllExchange}(C)
13:
                                                                     ▷ Update part sizes
14:
               C \leftarrow 0, A \leftarrow S
                                                              ▷ Reset per-task changes
15:
               mult \leftarrow update()
16:
               Q_{next} \leftarrow \emptyset
17:
          return D
```

Experimental Results

Test Environment and Graphs

Test systems:

- Blue Waters: 2x AMD 6276 Interlagos, 16 cores, 64 GB memory, up to 8192 nodes
- Compton: 2x Intel Xeon E5-2670 (Sandy Bridge), 16 cores, 64 GB memory, up to 16 nodes
- Test graphs:
 - UF Sparse Matrix, 10th DIMACS, SNAP, Max Planck Inst., Koblenz, Web Data Commons 2012 (WDC12) - social networks, web crawls, and meshes up to 128 billion edges
 - R-MAT, Erdős-Rényi (ER), High Diameter (HD) up to 1.1 trillion edges
- Test Algorithms:
 - PULP- multi objective and multi constraint
 - XTRAPULP- multi objective and multi constraint
 - ParMETIS single objective and multi constraint
 - KaHIP single objective and single constraint

Large Scale - Strong and Weak Scaling 256 - 2048 nodes of *Blue Waters*



Trillion Edge Tests

- Also attempted R-MAT, Erdős-Rényi, and high diameter graphs with 2³⁴ (17 billion) vertices and 2⁴⁰ (1.1 trillion) edges
- Ran on 8192 nodes of Blue Waters
- Erdős-Rényi partitioned in 380 seconds, high diameter in 357 seconds
- R-MAT graph failed; 2³⁴ vertex 2³⁹ edge R-MAT graph completed in 608 seconds
- No scalability bottlenecks for less skewed graphs; 1D representation limits further scalability for highly irregular graphs

Application Performance Partitioning WDC12

- At the large scale, how does increasing processor count affect partitioning quality for a fixed number of parts?
- Edge cut ratio stays below 0.07; vs. 0.16 for vertex block and over 0.99 for random
- Note: only competing methods at this scale are block and random/hash partitioning



Application Performance

 $HPCG{\tt RAPH} \ {\tt benchmark-https://github.com/HPCGraphAnalysis/HPCGraph}$

- 6 applications from HPCGRAPH- HC: harmonic centrality, LP: label propagation, SCC: strong connectivity, WCC: weak connectivity, PR: PageRank, KC: K-core
- 4 partitioning strategies Edge block, vertex block, random, XTRAPULP



Comparisons to Prior Work

Performance comparisons at smaller scale

- Multi-Constraint Scenario: Computing 16 parts of 26 test graphs on 16 nodes, XTRAPULP is 2.5x faster than PuLP and 4.6x faster than ParMETIS; on a single node, PULP is 1.5x faster than XTRAPULP
- Single-Constraint Scenario: Computing 2-256 parts of test graphs on a single node, XTRAPULP is about 1.36x slower than PULP, 6.8x faster than ParMETIS and 15x faster than KaHIP; on more nodes, speedups versus ParMETIS and KaHIP are consistent

Partitioner 🔶 XtraPuLP 📥 PuLP 🖶 ParMETIS — KaHIP



Comparisons to Prior Work

Quality comparisons at smaller scale

- Multi-Constraint Scenario: XTRAPULP is within 10% of PULP and ParMETIS for both edge cut and max cut objectives
- Single-Constraint Scenario: XTRAPULP cuts 8% more edges than PULP, 33% more than ParMETIS, and 50% more than KaHIP



Partitioner - XtraPuLP - PuLP - ParMETIS - KaHIP

What about X,Y parameters?

- Edge balance, edge cut, max per-part cut; values averaged across all small scale experiments; darker is worse, lighter is better
- Ideally, need to select values along *threshold* where lighter colors overlap to get both quality and balanced partitions
- Our values of X = 1.0, Y = 0.25 are selected empirically based on our experiments



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Conclusions and future work

- XTRAPULP scales to orders-of-magnitude larger graphs than prior art
- Efficient at all scales; quality comparable to state-of-the-art for multiple network types
- XTRAPULP code available: https://github.com/HPCGraphAnalysis/PuLP
- Interface also exists in Zoltan2 Trilinos package: https://github.com/trilinos/Trilinos
- Future work:
 - Explore 2D layouts for further scaling
 - Optimize communication and update methods
 - Explore techniques to improve quality

For papers, visit: www.gmslota.com, or email: slotag@rpi.edu

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