## Parallel Primitives for Computation with Large Graphs

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# Challenges [Lumsdaine et al. 2007]

- Graph computations are data-driven
  - Unpredictable communication patterns
- Irregular and unstructured nature
  - Poor locality
- Fine grained data accesses
  - Latency dominated



## An Architectural Approach - XMT

- Massively multithreaded machines
- No (or shallow) memory hierarchy
- Slower clock rates
- Uniform access time
- Highly scalable but not ubiquitous.





## **Our Approach – Sparse Matrices**

- Sparse matrix primitives
  - On special semirings
  - o (x,+); (and,or); (+,min); ....
- Oblivious
  - Fixed communication patterns
  - Easier to overlap communication
- Coarse grained parallelism
  - Exploit memory hierarchy





# BFS from multiple sources







# BFS from multiple sources



 Work efficient implementation using sparse matrix-matrix multiplication (SpGEMM)



# **SpGEMM** Applications

- Shortest path calculations (APSP)
- Betweenness centrality
- BFS from multiple source vertices
- Multigrid interpolation / restriction
- Subgraph / submatrix indexing
- Graph contraction
- Cycle detection
- Colored intersection searching
- Context-free parsing



## **SpGEMM** Data Distribution



- ID algorithms can not scale beyond 40x
- Break-even point is around 50 processors.



# 2D Example: Sparse SUMMA



- $C_{ij} += A_{ik} * B_{kj}$
- At worst doubles local storage

- Based on SUMMA
  (block size = n/sqrt(p))
- Easy to generalize nonsquare matrices, etc.



# Challenges of Parallel SpGEMM

- Scalable sequential kernel (A<sub>ik</sub> \* B<sub>ki</sub>)
- Load balancing
  - Especially for real world graphs
- Communication costs
  - Communication to computation ratio is much higher than dense GEMM
- Updates (additions)
  - o scalar additions ≠ scalar multiplications



# Submatrices are hypersparse !



Any data structure that depends on the matrix dimension n (such as CSR or CSC) is asymptotically too wasteful for submatrices



#### Trends of different components



UCSB

### Sequential Kernel [B&G 2008]

- Strictly O(nnz) data structure
- Complexity independent of matrix dimension
- Revival of outer-product formulation
- Heap assisted multi-way merging



#### Experiments with RMAT

#### Scalability of SpGEMM, RMAT\*RMAT

Scalability of SpGEMM, RMAT\*Perm



Only submatrix multiplications are timed

$$\sum_{i=0}^{\sqrt{p}}\sum_{j=0}^{\sqrt{p}}\sum_{k=0}^{\sqrt{p}}time(A_{ik}\times B_{kj})$$



#### Addressing the Load Balance

- Random permutations are useful.
- Bulk synchronous algorithms may still suffer:

#### Asynchronous algorithms have no notion of stages.



# **Overlapping Communication**

- Asynchronous, one sided communication (Again!)
- Can drop o from LogP model

#### GASNET, ARMCI

(Truly one-sided) Communication layers

Myrinet, Infiniband, etc

Hardware supporting zero copy RDMA



# Conclusions

- SpGEMM is a key primitive
- Much harder than dense GEMM
- No fixed recipe
  - It won't solve all your graph problems (as SpMV does not solve all your scientific problems)
- Highly scalable solution where applicable
- Widespread implementation on modern architectures (GPUs, Cell) would help.

